Three Dimensional Geometry

- Relation between the direction cosines of a line $l^2 + m^2 + n^2 1$ dinection cosines
- Dinection cosines of a line segment joining two points $P(x_1, y_1, z_1)$ and $Q(x_2, y_2, z_2)$ ane
 - $\frac{\chi_2 \chi_1}{PQ} = \frac{y_1 y_1}{PQ} = \frac{Z_2 Z_1}{PQ}$ where $PQ \cdot \sqrt{(\chi_2 \chi_1)^2 + (y_2 y_1)^2 + (Z_2 Z_1)^2}$
- Vecton Equation of a line that passes through the given point whose position vectors \vec{a} and parallel to a given vector \vec{b} is $\vec{n} = \vec{a} + \lambda \vec{b}$ (vector form) Cantesian Equation,

$$\frac{x-x_1}{l} = \frac{y-y_1}{m} = \frac{z-z_1}{n}$$

$$0R \qquad \frac{x-x_1}{a} = \frac{y-y_1}{b} = \frac{z-z_1}{c}$$
direction ratios

- Vector Equation of a line that passes through two points $\vec{n} = \vec{a} + \lambda(\vec{b} \vec{a})$, position vectors
- Cantesian Equation points: $(x_1, y_1, z_1)(x_2, y_2, z_2)$ $\frac{x x_1}{x_2 x_1} = \frac{y y_1}{y_2 y_1} = \frac{z z_1}{z_2 z_1}$
- If a1; b1; c1 and a2; b2; c2 are the direction ratios of two lines and 0 is the acute angle between two lines then; $COSO = \frac{a_1 a_2 + b_1 b_2 + c_1 c_2}{\sqrt{a_1^2 + b_1^2 + c_1^2} \sqrt{a_2^2 + b_2^2 + c_2^2}}$
 - Two lines with direction natios a, b, c, and a2, b2, c2 are
 - (1) penpendicular 0 = 90° $a_1 a_2 + b_1 b_2 + c_1 c_2 = 0$
 - $0 = 0^{\circ}$ $a_1 = b_1 = \frac{c_1}{c_1}$ (ii) panallel
 - If 0 is the acute angle between the line $\vec{n} = \vec{a_1} + \lambda \vec{b_1}$ and $\vec{n} = \vec{a_2} + \lambda \vec{b_3}$;
 - then θ is given by: $\cos \theta = \left| \frac{|\vec{b_1} \cdot \vec{b_2}|}{|\vec{b_1}||\vec{b_2}|} \right| \quad \text{or} \quad \theta = \cos^{-1} \frac{|\vec{b_1} \cdot \vec{b_2}|}{|\vec{b_1}||\vec{b_2}|}$ (vector form)
- The shontest distance between the lines $(\overrightarrow{b_1} \times \overrightarrow{b_2}) \cdot (\overrightarrow{a_2} - \overrightarrow{a_1})$ $\vec{n} = \vec{a_1} + \lambda \vec{b_1}$ and $\vec{n} = \vec{a_2} + \lambda \vec{b_2}$ is
 - Cantesian form, lines $\frac{x-x_1}{z-x_1} = \frac{y-y_1}{z-z_1} = \frac{z-z_1}{z-z_1}$ and $\frac{x-x_1}{z-x_1} = \frac{y-y_1}{z-z_1} = \frac{z-z_1}{z-z_1}$ is b_1 c_1

$$\begin{vmatrix}
\chi_2 - \chi_1 & y_2 - y_1 & z_2 - z_1 \\
\alpha_1 & b_1 & c_1 \\
\alpha_2 & b_2 & c_2
\end{vmatrix}$$

$$\frac{1}{\sqrt{(b_1 c_2 - b_2 c_1)^2 + (c_1 a_2 - c_2 a_1)^2 + (a_1 b_2 - a_2 b_1)^2}}$$

- Distance between Panallel lines $\vec{n} = \vec{a_1} + u\vec{b}$ and $\vec{n} = \vec{a_2} + u\vec{b}$ is
- Equation of a plane in a normal form Cantesian form, lx + my + nz = d
- n. n = d (vecton form) distance from origin
- $\vec{b} \times (\vec{a_2} \vec{a_i})$

The equation of a plane through a point whose position vector is a and perpendicular to the vector \vec{N} is $(\vec{n} - \vec{a}) \cdot \vec{N} = 0$ (vector form)

Cantesian form, $A(x-x_i) + B(y-y_i) + C(z-z_i) = 0$

Tequation of a plane passing through three non collinear points

$$(\vec{n} - \vec{a})[(\vec{b} - \vec{a})x(\vec{c} - \vec{a})] = 0$$
 (vector form)

Cantesian form,
$$x-x_1 \quad y-y_1 \quad z-z_1 \\ x_2-x_1 \quad y_2-y_1 \quad z_2-z_1 = 0 \\ x_3-x_1 \quad y_3-y_1 \quad z_3-z_1 = 0$$

I Plane passing through the intensection of two given planes $\vec{n} \cdot (\vec{n_1} + \lambda \vec{n_2}) = d_1 + \lambda d_2$

$$\frac{(\text{vecton form})}{\vec{n} \cdot (\vec{n_1} + \lambda \vec{n_2}) = d_1 + \lambda d_2}$$

Contesion form,
$$(A_1x + B_1y + C_1z - d_1) + \lambda(A_2x + B_2y + C_2z - d_2) = 0$$

Angle between two planes
$$\cos = \frac{|\vec{n_1} \cdot \vec{n_2}|}{|\vec{n_1}||\vec{n_2}|}$$

Cantesian form

Angle between a line and a plane $\cos \theta = \frac{\vec{b} \cdot \vec{n}}{|\vec{b}| |\vec{n}|}$

$$\cos\theta = \frac{\vec{b} \cdot \vec{n}}{|\vec{b}| \cdot |\vec{n}|}$$

the angle of between the line and the plane is given by 90°-0, i.e. Sin(90°-0) = coso

$$Sin\phi = \frac{\vec{b} \cdot \vec{n}}{|\vec{b}| \cdot |\vec{n}|}$$

$$sin\phi = \begin{vmatrix} \vec{b} \cdot \vec{n} \\ |\vec{b}| \cdot |\vec{n}| \end{vmatrix}$$
 OR $\phi = sin^{-1} \begin{vmatrix} \vec{b} \cdot \vec{n} \\ |\vec{b}| \cdot |\vec{n}| \end{vmatrix}$